

**Michael Avitabile**

Vice President of Engineering

Michael is an original member of the Torc Robotics Team dating back to the 2007 DARPA Urban Challenge and has been a part of Torc since our inception.

As the principal engineering leader, Michael oversees all aspects of engineering and ensures the organization operates optimally. His teams are responsible for all aspects of Torc's Autonomous Vehicle development, including Perception, Localization, Behaviors, Motion Planning, Machine Learning, Embedded Systems, Continuous Integration, product architecture, and other functions working collaboratively to achieve our mission.

Michael is a transformational leader who understands that people are our most important resource and the key to Torc's success. He has a propensity to identify talent, structure our technical strategies, and create our high-performance, winning-teams culture.

Michael believes in aligning our technology with educational institutions to create life-changing experiences that inspire young students to become disruptors who will help shape a safe and sustainable future.